

Large-Scale Cellular Coverage Analyses for UAV Data Relay via Channel Modeling

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The Internet of Things for Precision Agriculture an NSF Engineering Research Center





Rural Cellular Coverage Demand for broadband in rural areas

- Low population density
 - Not yet economically viable







Rural Cellular Coverage Demand for broadband in rural areas

- Not economically viable
 - Low user density, high customizability, and high infrastructure costs
- Digital agriculture
 - Over a vast low-population area
 - Basic data connection needed for sensors
 - High-speed connection for cameras
 - Intermittent connectivity requirement





"Dawn of Drones"

A vast array of new possibilities

- Extremely flexible
 - Aerial mobility
 - On-demand deployment
 - UAV-aided networks
 - Multi-tier architecture
 - Placement optimization
 - Route planning

- Uncertainties
 - Battery life
 - Safety
 - Legislation
 - Privacy

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Real-life deployment?

A series of <mark>quantitative</mark> analyses for large geographic areas based on real-life data

- Key findings
 - Upper bounds on system-level coverage gains
 - For example, ~45% cellular coverage ratio gain in IN with UAVs@100 m (baseline: 1.5 m)





Data Relay Scenario





Goals

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Coverage analysis and visualization

- Blockage maps
 - Simple and intuitive
 - LiDAR data
- Path loss maps





- Based on the NTIA^{*} eHata model
- Terrain elevation data
- Take into consideration more factors like reflection, refraction, terrain profile, obstacle clutter type...

^{*} National Telecommunications and Information Administration



Large-Scale



All about computation

- Areas of interest
 - ACRE (a Purdue research farm)
 - Tippecanoe County
 - WHIN (10 counties)
 - Indiana State





Large-Scale

- Indiana State
 - On-demand elevation
 - 322 GB LiDAR
 - => <mark>939</mark> GB locally cached data (as .mat files)
- Cluster
 - 36 cores
 - 216 GB RAM
 - >2 TB hard drive
 - <mark>~285</mark> GFLOPS

All about computation



(a) Front view



(b) Back view



Simulator Structure



Fig. Illustration diagram for the structure of the simulator





Cellular Towers



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Cellular tower locations obtained from the Commerce Spectrum Management Advisory Committee (CSMAC)



Inspected Locations





Channel Modeling

The LoS blockage case as an example



Fig. Determining blockage status

We used the raster LiDAR dataset (5 feet resolution) from the Indiana Statewide Imagery and LiDAR Program.

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Blockage Maps



Animation for the WHIN area, showing UAV flying at heights of

- 1.5 m,
- 10 m, and
- 100m.





Blockage Maps



(a) UAV height = 1.5 m



Cell towers

×

×

Clear

Blocked



(c) UAV height = 100 m





Blockage Maps



Fig. Clear LoS coverage ratio based on blockage maps

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Coverage Maps



Animation for the WHIN 150 area, showing UAV flying at heights of 140

- 1.5 m,

130

120

110

100

90

80

- 10 m, and
- 100m.





ERSI

Coverage Maps







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Coverage Maps



(a) UAV height = 1.5 m



(b) UAV height = 10 m



(c) UAV height = 100 m





Preliminary Results for IN





(b) Blockage maps



(c) Coverage maps **PURDUE** UNIVERSITY



Preliminary Results for IN





Contributions

A series of <mark>quantitative</mark> analyses for large geographic areas based on real-life data

- Key findings
 - Upper bounds on system-level coverage gains
 - For example, ~45% coverage ratio gain in IN with UAVs@100 m (baseline: 1.5 m)
 - More improvement expected for areas with larger elevation variation



Thank you!

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